

Physically-coherent Extraction of Mitral Valve Chordae

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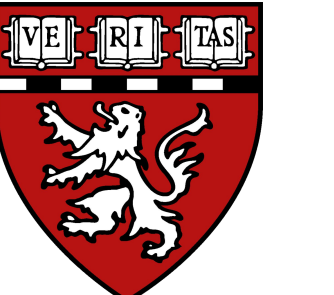
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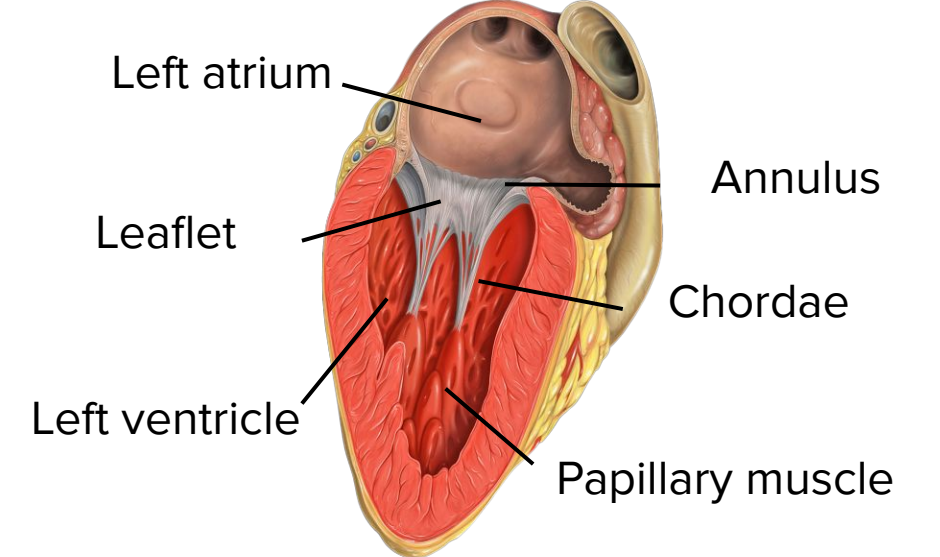


Introduction

- Mitral valve computational modeling could allow to improve the repair techniques.
- Modeling process includes extraction of the valve geometry:
 - Early works used generic geometries (based on *ex-vivo* measurements).
 - Recent works use *subject-specific* image-based geometries, which implies **manual** or **semi-manual** segmentation.

Goal:

- Semi-automatic extraction of the valve anatomic components (**chordae**).
- Validation with a biomechanical simulation.



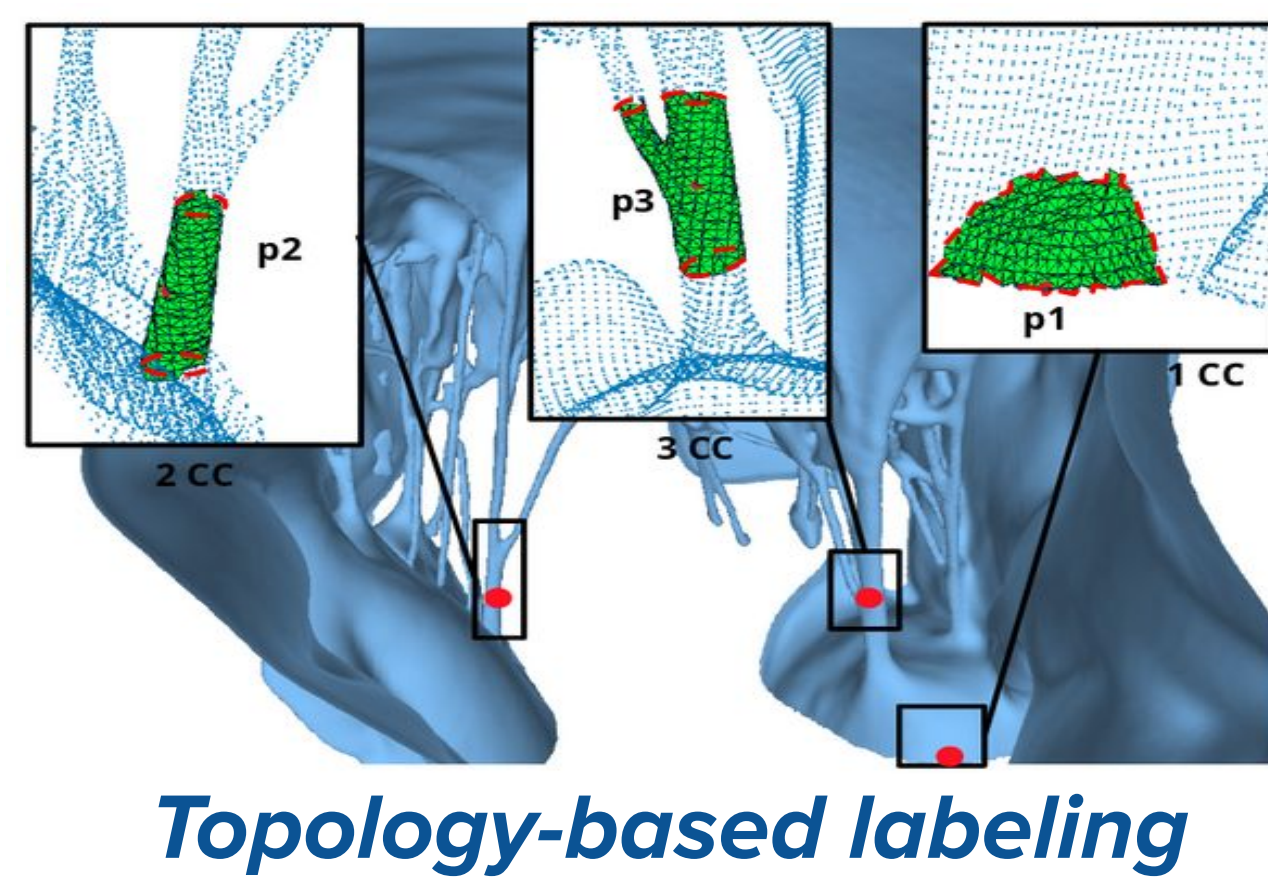
Mitral valve anatomy

Segmentation

Chordae

Topology-based method^[2]:

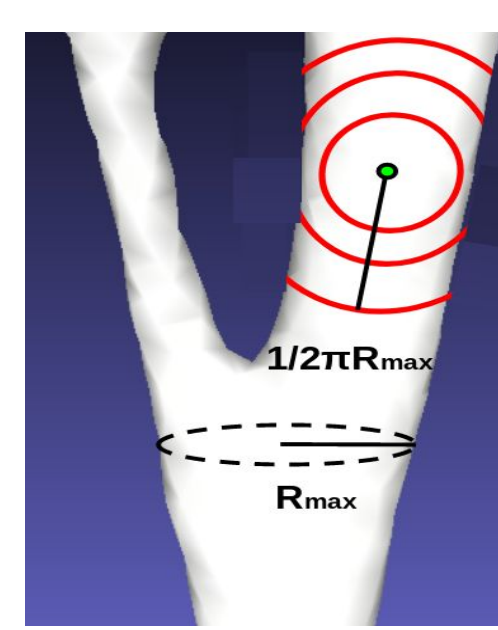
- Extract a submesh centered on a point (1).
- Label points of a mesh depending on the # of **connected components** of a corresponding submesh (2).



Topology-based labeling

1. Submesh extraction (max chordae size R_{max} is used as a parameter):

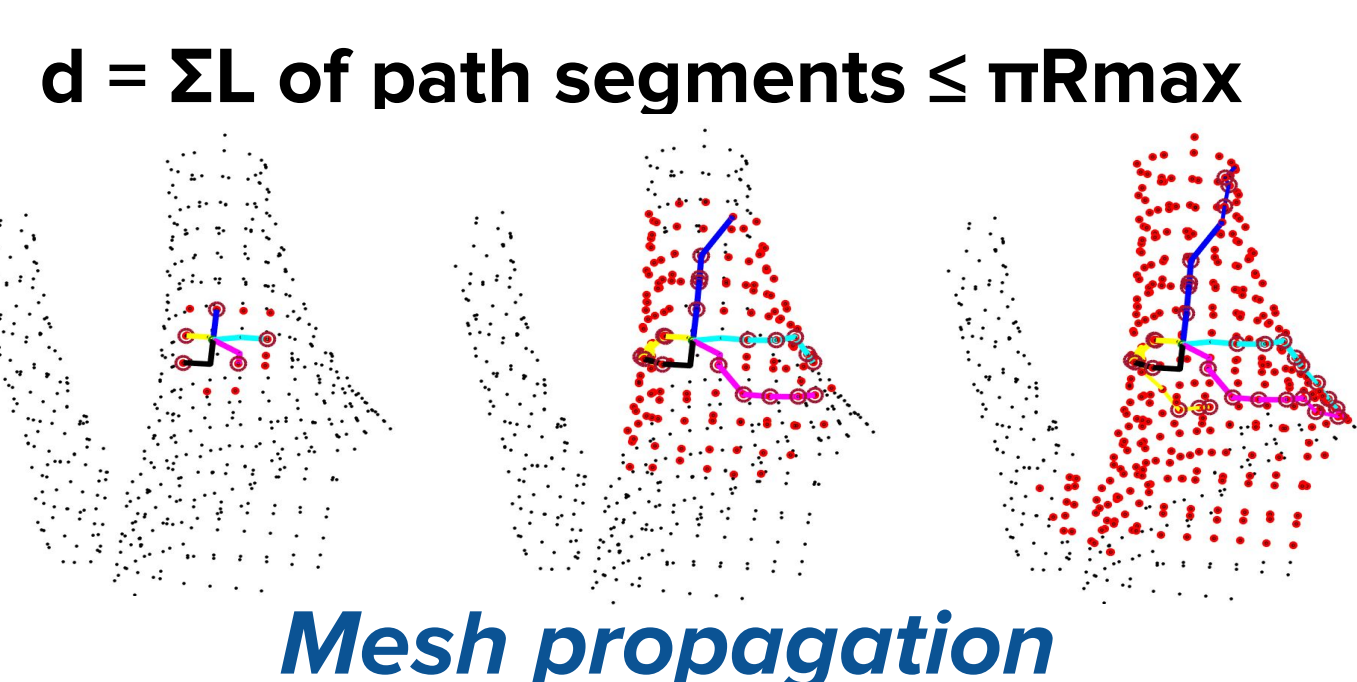
- Submesh includes points at geodesic distance d (in iso-geodesic contour)
- $d \leq \frac{1}{2} \max \text{chordae circumference} \leq \pi R_{max}$.



Submesh

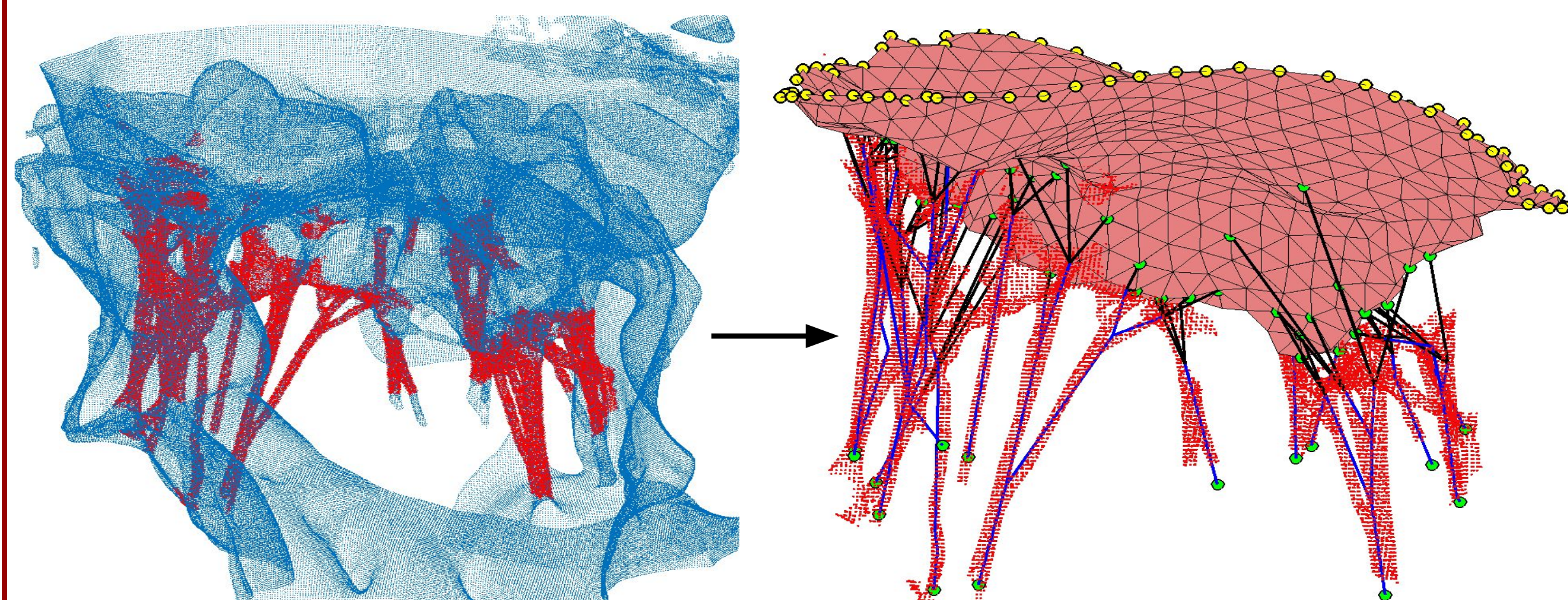
2. Labeling process:

- Geodesic distances calculation approximated with in-mesh propagation approach.



Mesh propagation

- All points of a submesh are labeled.



Segmentation result

Valve geometry in model

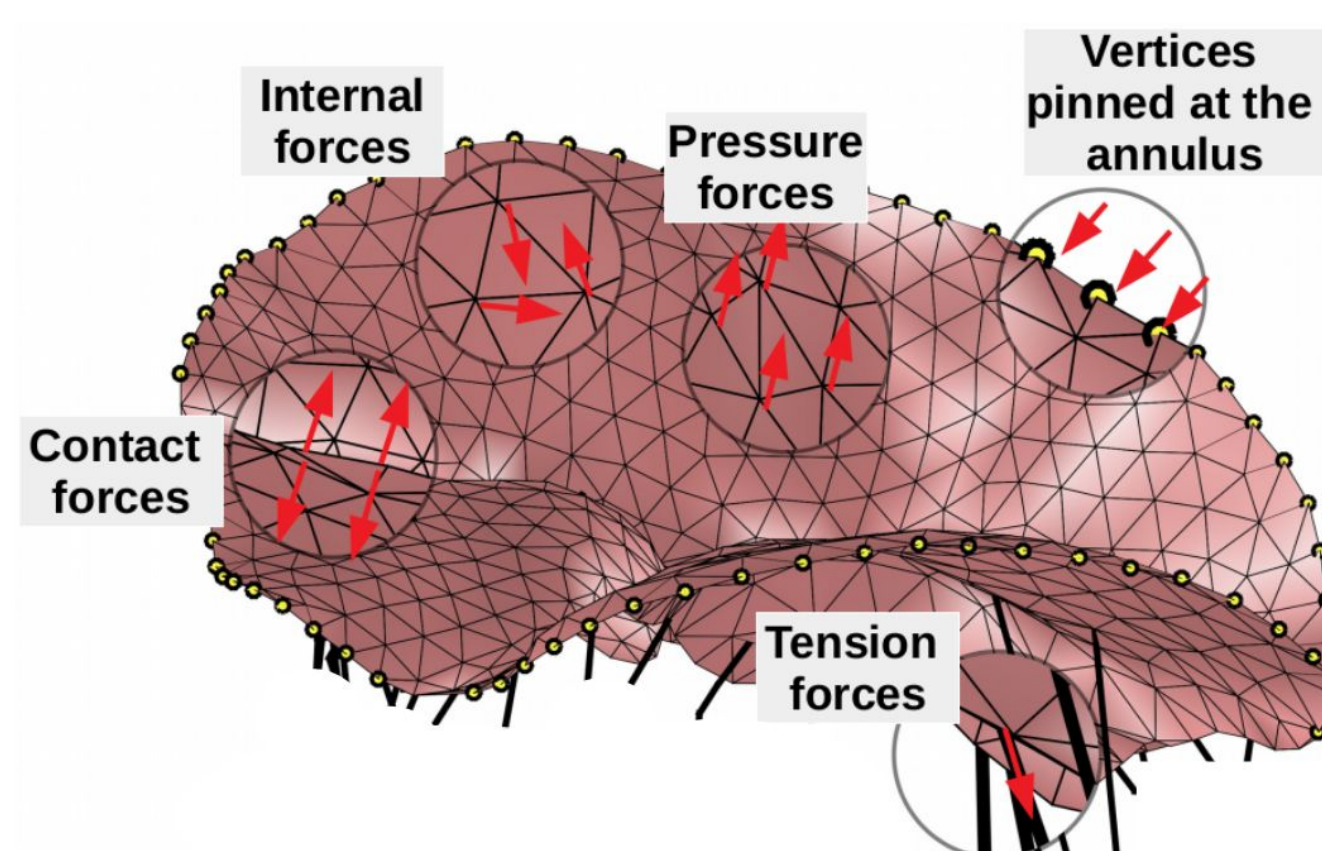
Leaflets and chordae geometry

- Leaflets** segmented manually and represented as a **triangulated mesh**.
- Annulus** points detected manually and fixed.
- Chordae** represented as a set of connected cylinders with bifurcation zones (**center-lines** of the cylinders and **centers of gravity** of bifurcation zones).
- Fan-like attachment of chordae in transition zone.

Mechanical model

FEM-based structural (no fluid interaction) model^[1]. Physiological behavior is simulated by the following boundary conditions:

- Pressure:** diastolic pressure = 120 mmHg.
- Tension forces:** applied to the leaflet vertices tethered to the chordae.
- Contact forces:** used to avoid the collisions along the zone of leaflet coaptation.
- Fixed points:** leaflet vertices along the valve annulus and chordae origins on papillary muscles.



Forces applied

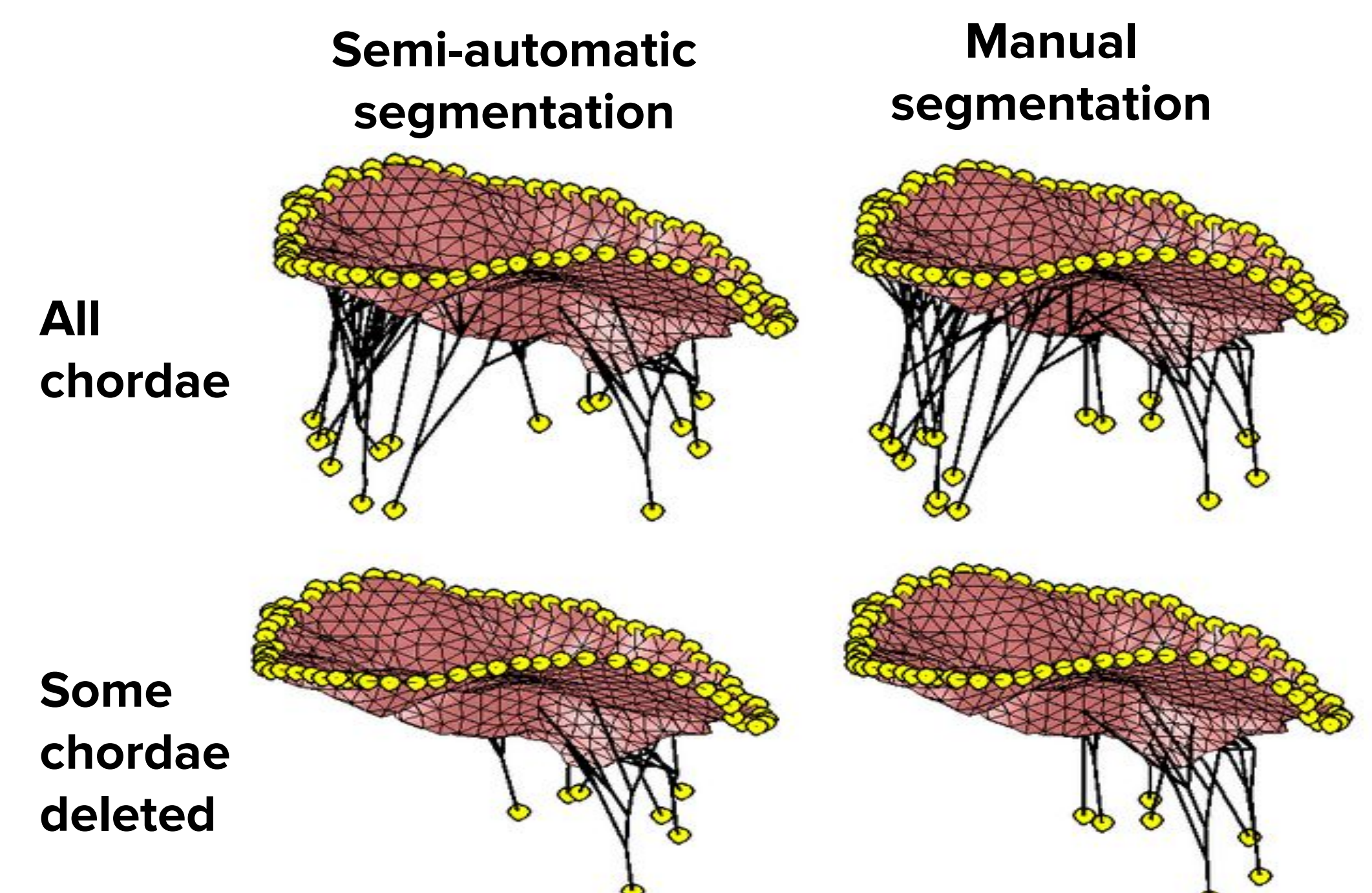
Finite element simulation:

- Dynamic approach: more straightforward and robust.
- Large deformation FE model based on 3-nodes membrane elements.
- Constitutive law: nonlinear, anisotropic in-plane response with no bending stiffness.
- Solved by semi-implicit numerical integration.

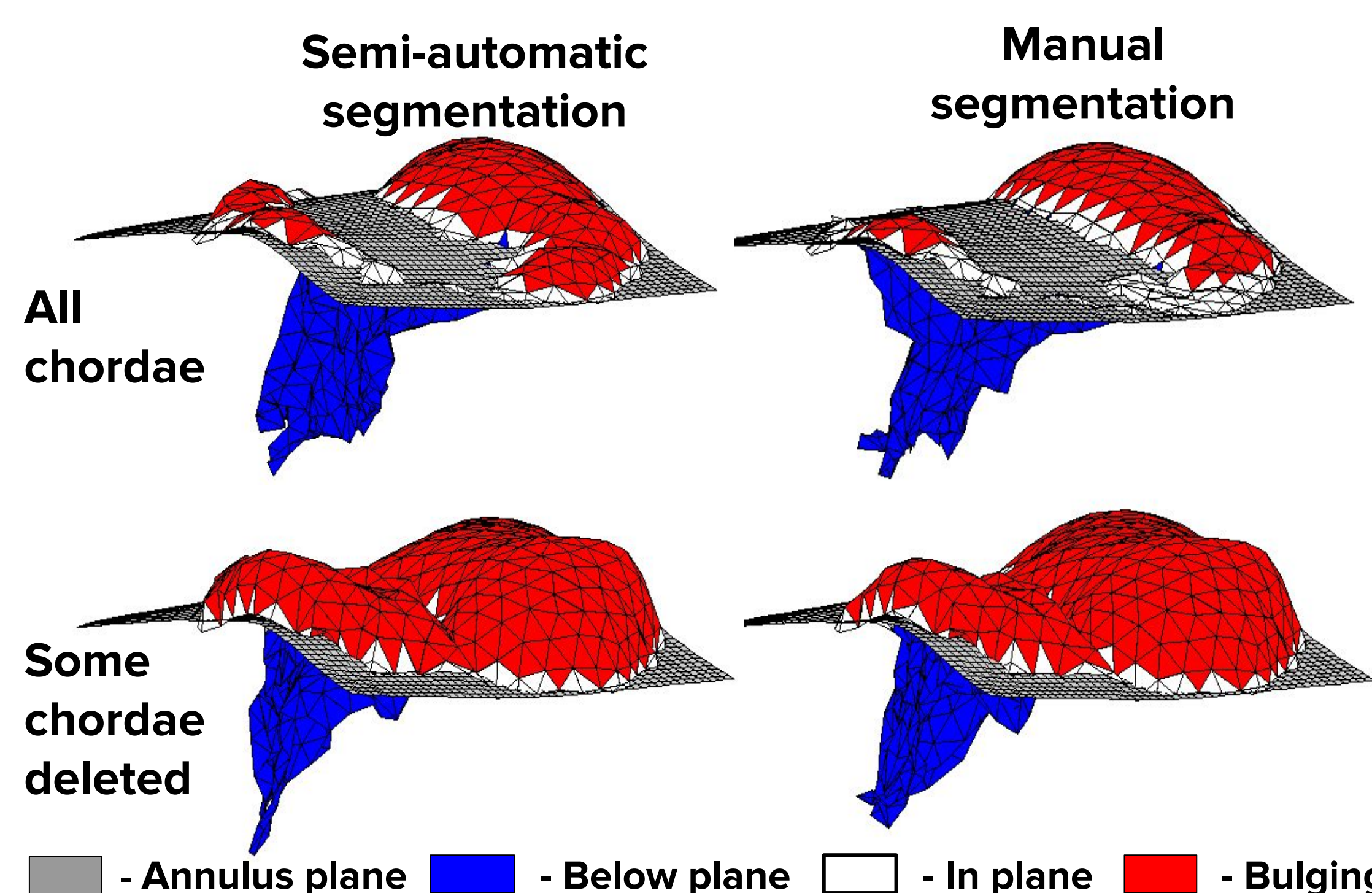
Results

Validation:

- Simulation is coherent:
 - Sealed** when all chordae present.
 - Bulging** and **leaks** when some chordae deleted.
- Simulation outcomes for semi-automatic and completely manual approaches correspond:
 - Von Mises stress distribution.
 - Bulging volume.



Simulation cases



Bulging volumes

| | Semi-auto | Manual |
|---|-----------|--------|
| Bulging vol. increase (all vs deleted) | 210% | 250% |

Conclusion and future work

- A method allowing the semi-automatic mitral valve chordae segmentation was proposed.
- Simulation outcomes obtained with the valve geometry being segmented semi-automatically are comparable to the results in the case of completely manual pipeline.
- Future work will concern the development of a semiautomatic solution for leaflet segmentation => allow us to validate the proposed approach on more datasets.

References

- [1] Hammer PE, del Nido PJ, Howe RD. *Anisotropic mass-spring method accurately simulates mitral valve closure from image-based models*. In Functional Imaging and Modeling of the Heart. Berlin, Heidelberg: Springer Berlin Heidelberg, 2011; 233–240.
- [2] Panicheva D, Villard PF, Berger MO. *Toward an automatic segmentation of mitral valve chordae*. In SPIE Medical Imaging, volume 10953. 2019; 4p.