

Localization Guided Speech Separation

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OVERVIEW

SPEECH SEPARATION USING LOCATION INFORMATION





▶ Use the location information to electronically steer towards the speaker

- Figure: Time-Frequency representation of speech
- Mixture contains speech from two speakers and noise
- ► Typically happens in devices such as Alexa and Google Home

- Extract features to estimate a mask
- ► Use mask along with beamformers to extract the speaker





- Interested only in the speaker interacting the device
- Recover speech using speaker location information
- Two step process:

6000

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2000

- Estimate speaker location using known keyword
- Using the location information to extract the interested speech

SPEAKER LOCALIZATION



Δ DOA	$< 10^{\circ}$		>50°		Average	
Beamformers	True DOA	Est DOA	True DOA	Est DOA	True DOA	Est DOA
GEV	38.0	54.5	30.2	41.5	30.9	43.2
R1-MWF	37.4	53.9	28.8	40.4	29.4	42.4
SDW	36.6	54.0	29.0	40.9	29.6	42.4

Table: Word error rate(%) on noisy two-speaker mixtures after separation using ground truth or estimated speaker location information (Using GCC-PHAT).

CONCLUSION

- Knowledge of text improves localization performance
- Can use localization information to improve separation performance
- Assumes knowledge of keyword like Alexa, Ok Google
- Words can be broken into phones. Example Alexa: AH L EH K S AH
- Phones has patterns. Use pattern to improve localization



Extended this approach to estimate speakers using deflation strategy

PUBLICATIONS

- Sunit Sivasankaran, Emmanuel Vincent, Dominique Fohr, *Keyword-based* speaker localization: Localizing a target speaker in a multi-speaker environment, Interspeech 2018
- Sunit Sivasankaran, Emmanuel Vincent, Dominique Fohr, Analyzing the impact of speaker localization errors on speech separation for automatic speech recognition, ICASSP 2020 (submitted)
- Sunit Sivasankaran, Emmanuel Vincent, Dominique Fohr, *SLOGD*: Speaker Location Guided Deflation Approach to Speech Separation, ICASSP 2020 (submitted)